

WEST Search History

DATE: Thursday, April 03, 2008

<u>Hide?</u>	<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>
		<i>DB=USPT; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L46	(("7053579" "6917176" "3851769" "4166543" "4791588")!.PN.). p68-p154.	5
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L45	(toggle or switch\$3 or slect\$3) and L44	6
<input type="checkbox"/>	L44	(open or close)gate and L43	10
<input type="checkbox"/>	L43	L34 and L42	152
<input type="checkbox"/>	L42	(error or fault or malfunction) and robot\$6 and L41 (700/245 700/246 700/251 700/253 700/260 700/261 318/568.1	1557
<input type="checkbox"/>	L41	318/568.12 318/568.16 318/568.17 318/568.2 901/1 901/9 901/46 180.1).ccls.	3807
<input type="checkbox"/>	L40	(5024920 5173382 5490103 5557564 5901829 6201488 6521838 6518503 6695663 6592418 5733819 6027554 6663326 6694847 6685863 4252414 4588518 4561746 4719331 5118090 5434926 5419740 5558196 5527940 5716481).pn.	47
<input type="checkbox"/>	L39	(5024920 5173382 5490103 5557564 5901829 6201488 6521838 6518503 6695663 6592418 5733819 6027554 6663326 6694847 6685863 4252414 4588518 4561746 4719331 5118090 5434926 5419740 5558196 5527940 5716481).pn.	47
<input type="checkbox"/>	L38	motion pattern and L36	2
<input type="checkbox"/>	L37	motion pattern and stor\$3 and L36	0
<input type="checkbox"/>	L36	freedom and L35	5
<input type="checkbox"/>	L35	L33 and L34	6
<input type="checkbox"/>	L34	L33 and gait or gate	1180657
<input type="checkbox"/>	L33	('6580969' '6493606' '6463356' '6289265' '6243623' '5872893' '5841258' '5838130' '5594644' 'EP 1136193A' 'EP 1103451A')!.ABPN1, NRPN,PN,TBAN,WKU.	18

<input type="checkbox"/>	L32	('20030019671' l'20020138359' l'6591923' l'6458011')!.ABPN1,NRPN,PN, TBAN,WKU.	7
<input type="checkbox"/>	L31	(legged robot or pet robot or humanoid near10 robot) motion and pattern	13
<input type="checkbox"/>	L30	(legged robot or pet robot or humanoid near10 robot) motion and pattern and L29	0
		(6252544 6493606 6243623 6289265 5673367 5355064 5455497 5325031 5357433 5594644 6580969 6718231 5504841 5842533 4621333 4633059 4987527 5937398 6064168 6429812 6584377 5259064 5349646 5946041 4540211 4762261 5273296 5616917 5627440 5794621 6059092 6059092 6068201 6456728 6505098 6711469 5402050 5525883 5841258 6463356 4614504 5040626 5343397 5369346 5378969 5644204 5672924 5838130 5872893 6229552).pn.	97
<input type="checkbox"/>	L28	stop\$4 and L27	3
<input type="checkbox"/>	L27	inner and L26	6
<input type="checkbox"/>	L26	motion\$ and L25	11
<input type="checkbox"/>	L25	L23 and L24	12
<input type="checkbox"/>	L24	command or instruction\$ and L23	784096
<input type="checkbox"/>	L23	sensor\$ and L22	12
<input type="checkbox"/>	L22	detection and L21	12
<input type="checkbox"/>	L21	correction and L20	17
<input type="checkbox"/>	L20	(error or fault or malfunction) and L19	25
		(10/515274 or 10/683496 or 10/805708 or 11/002627 or 11/200395 or 11/480126 or 09/663991 or 10/398070 or 10/477452 or 10/498149 or 10/508062 or 10/726597) or (6580969 or 6802382 or 6901313 or 6961640 or 6898485 or 6697709 or 6832131 or 6832132 or 6992455 or 7076337 or 7054718 or 7072740 or 7013201 or 7076338 or 7031806 or 7099747 or 7113849).pn.	46
<input type="checkbox"/>	L18	L2 and L17	13
<input type="checkbox"/>	L17	computer and L16	618
<input type="checkbox"/>	L16	input\$4 and L15	623
<input type="checkbox"/>	L15	motion and (sensor or camera)and correct\$ and L14	668
<input type="checkbox"/>	L14	(edit\$3 or updat\$3 reprogram or "re-program") and L13	2655

		robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant)	5449
□	L13	('6711469' l'6697709' l'6567724' l'6505098' l'6493606' l'6480761' l'6330494' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
□	L11	marc.xa. and legged and inclination	33
□	L10	marc.xa. and legged and inclinaiton	0
□	L9	robot and motion generation and time	81
□	L8	robot and motion generation and time same sequential	1
□	L7	(5936367 5355064).pn.	4
□	L6	('6901313' l'6898485' l'6832132' l'6832131' l'6802382' l'6697709' l'6580969')!.ABPN1,NRPN,PN,TBAN,WKU.	15
□	L5	(6832132 6832131 6697709 6898485 6901313 6802382 6580969).pn.	15
□	L4	request\$3 and L3	39
□	L3	priority and data same transfer and L2	48
□	L2	robot controller and switch and switch\$3 and interface and motion\$	367
□	L1	5621672.pn.	2

END OF SEARCH HISTORY